

Excursions on rough paths

(Or, thoughts about the integration of irregular functions)

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Prologue.

(or, what not to expect)

- You will hear something about rough paths, however. . .
- There will be very little rough paths (at least in the form you could expect)
- There will be **no** reference to probability (but stochastic analysis is the main application)
- Enjoy the open landscape

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Outline

1 Increments

- Abstract integration
- Exercise of deconstruction
- Rough paths

2 Variations

- Convolution integrals
- Multiparameter integrals

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- **Abstract integration**
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2 Variations

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k -Increments

Definition

A k -increment is a continuous function $g : [0, T]^{k+1} \rightarrow V$ such that $g_{t_0 \dots t_k} = 0$ whenever $t_i = t_{i+1}$. Denote them $\mathcal{C}_k(V)$.

Example

- $g \in \mathcal{C}_0$ is a function on $[0, T]$
- Given $f \in \mathcal{C}_1$, set $g_{ts} = f_t - f_s$, then $g \in \mathcal{C}_1$.

Basic fact

$g \in \mathcal{C}_1$ is given by $g_{ts} = f_t - f_s$ for some $f \in \mathcal{C}_0$ iff it satisfy

$$g_{ts} - g_{su} - g_{us} = 0$$

A cocycle property.

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A **cocycle** property.

A cochain complex

- Increments forms a cochain complex (\mathcal{C}_*, δ) with coboundary map

$$\delta : \mathcal{C}_k \rightarrow \mathcal{C}_{k+1} \quad (\delta g)_{t_1 \dots t_{k+1}} = \sum_{i=1}^{k+1} (-1)^i g_{t_1 \dots \hat{t}_i \dots t_{k+1}}$$

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$$\mathcal{C}_0 \xrightarrow{\delta} \mathcal{C}_1 \xrightarrow{\delta} \mathcal{C}_2 \xrightarrow{\delta} \mathcal{C}_3 \xrightarrow{\delta} \dots$$

$\delta\delta = 0$ and $\text{Ker}\delta|_{\mathcal{C}_{k+1}} = \text{Im}\delta|_{\mathcal{C}_k}$ so the complex is **acyclic**.

- In particular, $g \in \mathcal{C}_1$ is a **1-cocycle** (or closed 1-increment) if

$$\delta g_{tus} = -g_{us} + g_{ts} - g_{tu} = 0.$$

Then there exists $f \in \mathcal{C}_0$ such that $g = \delta f$: closed 1-increments are **exact**.

- (cfr. de-Rham cohomology of \mathbb{R}^n : closed differential forms are exact)

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Some (useful) notation...

Definition

For $a \in \mathcal{C}_k$ and $b \in \mathcal{C}_m$ we define the product $ab \in \mathcal{C}_{k+m}$ as

$$(ab)_{t_1 \dots t_{k+m+1}} = a_{t_1 \dots t_{k+1}} b_{t_{k+1} \dots t_{k+m+1}}$$

Notation

When $x, f_1, f_2 \in \mathcal{C}_0$ and smooth, we will mean

$$\left(\int \varphi(x) dx \right)_{ts} = \int_s^t \varphi(x_r) dx_r$$

and

$$\left(\int df_1 df_2 \right)_{ts} = \int_s^t \left(\int_s^u d_r f_{1,r} \right) d_u f_{2,u}$$

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... and interesting relations

- Easy to check:

$$\delta \int df_1 = 0 \quad \delta \int df_1 df_2 = \int df_1 \int df_2 = \delta f_1 \delta f_2$$

for any smooth $f_1, f_2 \in \mathcal{C}_0$.

- And more generally

$$\delta \int df_1 \cdots df_n = \sum_{k=1}^{n-1} \int df_1 \cdots df_k \int df_{k+1} \cdots df_n$$

- Moral: δ splits iterated integral into “simpler” objects (and \wedge put them together again...)

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Norms on Increments

Definition

For $g \in \mathcal{C}_1, h \in \mathcal{C}_2$ let

$$\|g\|_\mu = \sup_{t,s \in [0,T]} \frac{|g_{ts}|}{|t-s|^\mu} \quad \|h\|_{\rho,\sigma} = \inf \sup_{t,s,u \in [0,T]^3} \frac{|h_{tus}|}{|t-u|^\rho |u-s|^\sigma}$$

and

$$\|h\|_\mu = \inf \left\{ \sum_i \|h_i\|_{\rho_i, \mu - \rho_i} : h = \sum_i h_i, 0 < \rho_i < \mu \right\}$$

Denote \mathcal{C}_k^μ the subset of \mathcal{C}_k with finite $\|\cdot\|_\mu$ norm ($k = 1, 2$).
Let $\mathcal{C}_k^{1+} = \cup_{\mu > 1} \mathcal{C}_k^\mu$ – the **small** increments.

The Λ map

Fact

We have $\mathcal{BC}_1^{1+} = \mathcal{C}_1^{1+} \cap \text{Im}\delta = \{0\}$: nontrivial small 1-increments cannot be exact.

Theorem

There exists a unique bounded linear map $\Lambda : \mathcal{BC}_2^{1+} \rightarrow \mathcal{C}_1^{1+}$ such that

$$\delta\Lambda g = g.$$

$$(\mathcal{BC}_2^{1+} = \mathcal{C}_2^{1+} \cap \text{Im}\delta)$$

If $g \in \mathcal{C}_1$ and $\delta g \in \mathcal{C}_2^{1+}$, then

$$g = \Lambda\delta g + \delta f$$

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1 Increments

- Abstract integration
- **Exercise of deconstruction**
- Rough paths

2 Variations

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What an integral is made of?

Taylor formula

$$\int_s^t \varphi(x_r) dx_r = \varphi(x_s) \int_s^t dx_r + \int_s^t \left(\int_s^u \varphi'(x_r) dx_r \right) dx_u$$

with our “brand new” notation reads

$$\int \varphi(x) dx = \varphi(x) \int dx + \int \varphi'(x) dx dx$$

as elements of \mathcal{C}_1 .

We look in more detail to the iterated integral by **dissecting** it:

$$\delta \int \varphi'(x) dx dx = \int \varphi'(x) dx \int dx = \delta \varphi(x) \delta x \in \mathcal{C}_3^2$$

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Young integration

- Then

$$\int \varphi(x) dx = \varphi(x)\delta x + \Lambda(\delta\varphi(x)\delta x)$$

- The integral on the l.h.s is equal to an expression which do not need x to be differentiable.
- Essentially x must be γ -Hölder with $\gamma > 1/2$ – **Young integration**

Go on...

Again

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But now continue Taylor expansion one step further:

$$\int \varphi(x) dx = \varphi(x) \int dx + \varphi'(x) \int dx dx + \int \varphi''(x) dx dx dx$$

The remainder is now a three-fold integral:

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Putting things together

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(if the argument of Λ is small enough).

- To make sense of the r.h.s we need a small $\int dx dx$ such that

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(which is a highly nontrivial non-linear relation).

- $\int dx dx$ is the “Levy area” of the rough path theory.

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Rougher and rougher.

- This procedure can be iterated to recover the hierarchy of (Lyons') rough paths which are given by a sequence of iterated integrals of the form

$$\int dx, \quad \int dx dx, \quad \int dx dx dx, \dots$$

- **Watch out:** to prove smallness of some terms we need **geometric** rough paths, i.e. which satisfy relations like

$$[(\delta x)_{st}]^2 = 2 \left(\int dx dx \right)_{ts}.$$

(smooth integrals OK, Stratonovich OK, Itô NO! – but we do not need it).

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Increments of convolutions

Let $S(t) = e^{-\lambda t}$, $t \geq 0$ a (semi-)group of contractions on the real line.
Look at

$$g_t = \int_0^t S(t-u)\varphi(x_u)dx_u$$

Then

$$(\delta g)_{ts} = a_{ts}g_s + \int_s^t S(t-u)\varphi(x_u)dx_u$$

with $a_{ts} = S(t-s) - 1$

The perturbed complex

Idea

Introduce the “perturbed” coboundary $\hat{\delta} = (\delta - a)$

- $\hat{\delta}\hat{\delta} = 0$ using $\delta a = aa$
- We have another **acyclic** cochain complex $(\mathcal{C}_*, \hat{\delta})$

$$\mathcal{C}_0 \xrightarrow{\hat{\delta}} \mathcal{C}_1 \xrightarrow{\hat{\delta}} \mathcal{C}_2 \xrightarrow{\hat{\delta}} \mathcal{C}_3 \xrightarrow{\hat{\delta}} \dots$$

- There exists a unique bounded operator $\hat{\Lambda} : \mathcal{BC}_2^{1+} \rightarrow \mathcal{C}_1^{1+}$ such that

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A (bi-)linear equation

Let us play with the solution y of the (bi-)linear integral equation

$$y_t = S(t-s)y_s + \int_s^t S(t-u)dx_u y_u.$$

Expand the r.h.s. in a truncated series of iterated integrals:

$$y_t = S(t-s)y_s + \int_s^t S(t-u)dx_u S(u-s)y_s + \int_s^t S(t-u)dx_u \int_s^u S(u-v)dx_v y_v$$

In our notation this reads:

$$\hat{\delta}y = y \int \tilde{d}x + \int \hat{d}x(\hat{d}x y) = y \int \tilde{d}x + y \int \hat{d}x \tilde{d}x + \int \hat{d}x \hat{d}x(\hat{d}x y)$$

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Convolution rough paths

- Working a bit we get to

$$\hat{\delta}y = (1 - \hat{\Lambda}\hat{\delta}) \left[y \int \tilde{dx} + y \int \hat{dx}\tilde{dx} \right]$$

where we used the fact that $\hat{\delta} \int \hat{dx}\tilde{dx} = \int \tilde{dx} \int \tilde{dx}$

- This express the solution y as a function of the couple

$$\int \tilde{dx} \quad \int \hat{dx}\tilde{dx}$$

suitable notion of rough path for convolution equations.

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Outline

- 1 Increments
 - Abstract integration
 - Exercise of deconstruction
 - Rough paths

- 2 Variations
 - Convolution integrals
 - Multiparameter integrals

2d Integrals

- With regular $f, g : \mathbb{R}^2 \rightarrow \mathbb{R}$ define 2d integrals as

$$\iint_{(x_1, y_1)}^{(x_2, y_2)} fdg := \int_{x_1}^{x_2} dx \int_{y_1}^{y_2} dy f(x, y) \partial_1 \partial_2 g(x, y)$$

- ∂_1 and ∂_2 are the partial derivatives wrt. the first and the second coordinate, respectively.
- Another possibility, for a triple f, g, h

$$\iint_{(x_1, y_1)}^{(x_2, y_2)} fd_1gd_2h := \iint_{(x_1, y_1)}^{(x_2, y_2)} f(x, y) \partial_1 g(x, y) \partial_2 h(x, y) dx dy$$

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2d exact increments

- Then

$$\begin{aligned}\iint_{(x_1, y_1)}^{(x_2, y_2)} dg &= g(x_2, y_2) - g(x_1, y_2) - g(x_2, y_1) + g(x_1, y_1) \\ &=: (\delta g)(x_1, y_1, x_2, y_2)\end{aligned}$$

which identify the natural “two-dimensional” increment δg of a function g .

The complex of 2d increments

In complete analogy with the 1-d case we have:

- 2-d cochains $\mathcal{C}_{k,l}$ which are k -increments in the first direction and l increments in the second direction.
- 2-d coboundary map $\delta = \delta_1 \delta_2$ which is given by the successive application of 1-d coboundaries in the two directions.
- the complex

$$\mathcal{C}_{0,0} \xrightarrow{\delta} \mathcal{C}_{1,1} \xrightarrow{\delta} \mathcal{C}_{2,2} \xrightarrow{\delta} \mathcal{C}_{3,3} \xrightarrow{\delta} \dots$$

which is **not** acyclic.

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Expansion of 2d integrals

For a two-dimensional quantity we can write down the following expansion

$$\begin{aligned} \iint_{(x_1, y_1)}^{(x_2, y_2)} f(x, y) dg(x, y) &= -f(x_1, y_1)(\delta g)(x_1, y_1, x_2, y_2) \\ &+ \int_{y_1}^{y_2} f(x_1, y) d_2[g(x_2, y) - g(x_1, y)] + \int_{x_1}^{x_2} f(x, y_1) d_1[g(x, y_2) - g(x, y_1)] \\ &+ \iint_{(x_1, y_1)}^{(x_2, y_2)} \left[\iint_{(x_1, y_1)}^{(x, y)} df(u, v) \right] dg(x, y) \end{aligned}$$

We can set up a convenient notation in which this equation reads

$$\iint f dg = \underbrace{f \iint dg}_{f \delta g} + \underbrace{\int_1 f \int_2 dg + \int_2 f \int_1 dg}_{\text{boundary integrals}} + \underbrace{\iint df dg}_{\text{remainder}}$$

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2d dissection

Our preferred exercise:

$$\iint \varphi(x) dx = -\varphi(x) \int dx + \int_1 \varphi(x) \int_2 dx + \int_2 \varphi(x) \int_1 dx \\ + \iint d\varphi(x) dx$$

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$$\begin{aligned} \iint \varphi(x) dx &= -\varphi(x) \int dx + \int_1 \varphi(x) \int_2 dx + \int_2 \varphi(x) \int_1 dx \\ &+ \iint \varphi'(x) dx dx + \iint \varphi''(x) (d_1 x d_2 x) dx \end{aligned}$$

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Strategy to control the expansion

$$\begin{aligned} \iint \varphi'(x) dx dx &= -\varphi'(x) \int dx dx + \int_1 \varphi'(x) \int_2 dx dx \\ &+ \int_2 \varphi'(x) \int_1 dx dx + \iint d\varphi'(x) dx dx \end{aligned}$$

This expression seems complicated, however it shows that, in order to control the l.h.s. we need two ingredients:

- 1 Being able to define **essentially one-dimensional integrals** like

$$\int_1 \varphi(x) \int_2 dx, \int_1 \varphi'(x) \int_2 dx dx, \int_1 \varphi''(x) \int_2 d_1 x d_2 dx, \dots$$

- 2 Control the **remainders** given by the three-fold iterated integrals

$$\mathcal{R} := \iint d\varphi'(x) dx dx \quad \tilde{\mathcal{R}} := \iint d\varphi''(x) d_1 x d_2 dx.$$

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The boundary integrals (example)

$$\int_1 \varphi'(x) \int_2 dx dx = \varphi'(x) \iint dx dx - \Lambda_1 \left[\delta_1 \varphi'(x) \iint dx dx + \mathcal{C}_1 \right]$$

with

$$\mathcal{C}_1 := \varphi''(x) \int_1 d_1 x \int_2 dx \int_1 dx - (\Lambda_1 \otimes_1 1)(\mathcal{A}_1 + \mathcal{B}_1)$$

$$\mathcal{A}_1 := \delta_1 \varphi''(x) \int_1 d_1 x \int_2 dx \int_1 dx$$

and

$$\mathcal{B}_1 := (\delta_1 \varphi''(x) - \varphi''(x) \delta_1 x) \int_1 \int_2 dx \int_1 dx$$

The 2d rough sheet

To define integrals over a Brownian-like sheet x we need at least the following data:

$$\iint dx, \quad \iint d_1x d_2x, \quad \iint dx dx, \quad \iint d_1x d_2x dx,$$

$$\iint (d_1x d_2x)(d_1x d_2x), \quad \int_1 d_1x \int_2 dx \int_1 dx,$$

and some others...

Summary

- Lyons' rough paths seems the **tip** of an iceberg.
- **Flexibility** of the approach (many kinds of “rough paths” but same structure)
- *Sometimes* algebra is **useful** (and interesting).

- Outlook
 - ▶ Effective approach to path-wise SPDEs (more in S. Tindel talk).
 - ▶ A lot of work to do to fully understand rough sheets.
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