

Some infinite dimensionals rough-paths

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Rough paths

- ▶ T. Lyons (Oxford): an integration theory for irregular signals.
- ▶ Nonlinear systems y_t driven by a (non-differentiable) noise x_t

$$dy = f(y)dx$$

- ▶ The output y is a nice function of the iterated integrals of x :

$$\left(x, \int dx dx, \dots, \int dx^{\otimes n} \right) \xrightarrow{\Phi} y$$

We can consider only a finite number of them. No need of formal series.

Algebraically

The increment $\delta y_{ts} = y_t - y_s$ of the solution of the integral equation $y = \int f(y)dx$ has a natural expansion

$$\delta y_{ts} = \int_s^t f(y_u) dx_u = f(y_s) \int_s^t dx_u + f(y_s) f'(y_s) \int_s^t \int_s^u dx_w dx_u + \text{h.o.t.}$$

If we neglect the h.o.t. it belongs to the linear span of the iterated integrals

$$X_{ts}^1 = x_t - x_s \quad \dots \quad X_{ts}^n = \int_s^t X_{us}^{n-1} dx_u$$

and we write it as

$$[(fX)_{ts} = f_s X_{ts}]$$

$$\delta y = y^1 X^1 + y^2 X^2 + \dots$$

where $y_t^1 = f(y_t)$, $y_t^2 = f(y_t)f'(y_t)$, and so forth.

The solution of the ODE is identified with the fixed point of

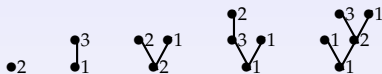
$$y \xrightarrow{\text{nonlinear map}} f(y) \xrightarrow{\text{integration}} I(f(y))$$

for y_s whose increments can be (partially) expanded on the $\{X^n\}_n$

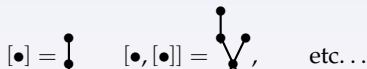
Phenomenology of rough-paths

Trees

\mathcal{L} finite set. Trees labeled by $\mathcal{L}, \mathcal{T}_{\mathcal{L}}$



$$(\tau_1, \dots, \tau_k) \xrightarrow{B_+^a} \tau = [\tau_1, \dots, \tau_k]_a$$



$$\Delta(\tau) = 1 \otimes \tau + \sum_{a \in \mathcal{L}} (B_+^a \otimes \text{id})[\Delta(B_-^a(\tau))]$$

$$B_-^a(B_+^b(\tau_1 \cdots \tau_n)) = \begin{cases} \tau_1 \cdots \tau_n & \text{if } a = b \\ 0 & \text{otherwise} \end{cases}$$

Differential equations (*à la Butcher*)

The solution y of the differential equation

$$dy = f(y)dt, \quad y_0 = \eta$$

has the B-series representation

$$y_t = \eta + \sum_{\tau \in \mathcal{T}} \psi^f(\tau)(\eta) \frac{t^{|\tau|}}{\sigma(\tau)\tau!}$$

Elementary differentials ψ^f defined as

$$\psi^f(\bullet)(\xi) = f(\xi), \quad \psi^f([\tau^1 \dots \tau^k]) = f_b(\eta) \psi^f(\tau^1)(\xi)^{b_1} \dots \psi^f(\tau^k)(\xi)^{b_k}$$

where $f_\emptyset(\xi) = f(\xi)$ and $f_b(\xi) = \prod_{i=1}^{|\bar{b}|} \partial_{\xi_{b_i}} f(\xi)$ derivatives of the vectorfields.

Driven differential equations

Given a collection of paths $\{x^a \in C^1([0, T], \mathbb{R})\}_{a \in \mathcal{L}}$, $\eta \in \mathbb{R}^n$

Analytic vectorfields $\{f_a : \mathbb{R}^n \rightarrow \mathbb{R}^n\}_{a \in \mathcal{L}}$

Theorem

The differential equation

$$dy_t = f_a(y_t) dx_t^a, \quad y_0 = \eta$$

admit locally the series solution

$$y_t = y_s + \sum_{\tau \in \mathcal{J}_{\mathcal{L}}} \frac{1}{\sigma(\tau)} \phi^f(\tau)(y_s) X_{ts}^\tau, \quad y_0 = \eta$$

where $\phi^f(\bullet_a)(\xi) = f_a(\xi)$, $\phi^f([\tau^1 \dots \tau^k]_a)(\xi) = f_{a; b_1 \dots b_k}(\xi) \prod_{i=1}^k [\phi^f(\tau^i)(\xi)]^{b_i}$.

Smooth iterated integrals

Let $X : \mathcal{T}_{\mathcal{L}} \rightarrow \mathcal{C}_2 \subset C([0, T]^2; \mathbb{R})$

$$X_{ts}^{\bullet a} = \int_s^t dx_u^a, \quad X_{ts}^{[\tau^1 \dots \tau^k]a} = \int_s^t \prod_{i=1}^k X_{us}^{\tau^i} dx_u^a. \quad (1)$$

Extend X to $\mathcal{AT}_{\mathcal{L}}$ considering \mathcal{C}_2 as an algebra with (commutative) product $(a \circ b)_{ts} = a_{ts}b_{ts}$ for $a, b \in \mathcal{C}_2$. We let $X^1 = 1$.

$$X_{ts}^{\tau_1 \dots \tau_n} = X_{ts}^{\tau_1} X_{ts}^{\tau_2} \dots X_{ts}^{\tau_n}, \quad X^{[\tau_1 \dots \tau_n]a} = \int X^{\tau_1 \dots \tau_n} dx^a$$

Bounds

$$|X_{ts}^{\tau}| \leq \frac{(A|t-s|)^{|\tau|}}{\tau!}$$

Theorem (Tree multiplicative property)

$$X_{ts}^{\tau} = \sum X_{tu}^{\tau(1)} X_{us}^{\tau(2)} = X_{tus}^{\Delta \tau}$$

Example

$$T_{ts}^\bullet = t - s, \quad T_{ts}^{[\tau_1 \cdots \tau_n]} = \int_s^t T_{us}^{\tau_1} \cdots T_{us}^{\tau_n} du$$

By induction: $T_{ts}^\tau = (t - s)^{|\tau|} (\tau!)^{-1}$

Lemma (Tree Binomial)

For every $\tau \in \mathcal{T}$ and $a, b \geq 0$ we have

$$(a + b)^{|\tau|} = \sum_i \frac{\tau!}{\tau_i^{(1)}! \tau_i^{(2)}!} a^{|\tau_i^{(1)}|} b^{|\tau_i^{(2)}|} \quad (2)$$

Structure of solution to DDEs

Write $y_s^\tau = \phi^f(\tau)(y_s)/\sigma(\tau)$ so that

$$y_t - y_s = \sum_{\tau \in \mathcal{T}_{\mathcal{L}}} X_{ts}^\tau y_s^\tau$$

Lemma

For any $\tau \in \mathcal{T}_{\mathcal{L}} \cup \{\emptyset\}$ we have

$$y_t^\tau - y_s^\tau = \sum_{\sigma \in \mathcal{T}_{\mathcal{L}}, \rho \in \mathcal{F}_{\mathcal{L}}} c'(\sigma, \tau, \rho) X_{ts}^\rho y_s^\sigma$$

c' counting function of reduced coproduct: $\Delta' \sigma = \sum_{\tau, \rho} c'(\sigma, \tau, \rho) \tau \otimes \rho$.

Integration of increments

- ▶ Q: Given $a \in \mathcal{C}_2$ can we find $f \in \mathcal{C}_1$ such that $f_t - f_s = a_{ts}$?
 $a_{ts} - a_{tu} - a_{us} = (f_t - f_s) - (f_t - f_u) - (f_u - f_s) = 0$ (obstruction)
- ▶ Increments: $\mathcal{C}_n \subset C([0, 1]^n, V)$, $g \in \mathcal{C}_n$ iff $g_{t_1 \dots t_n} = 0$ when $t_i = t_{i+1}$
Coboundary: $\delta f_{ts} = f_t - f_s$, $\delta g_{tus} = g_{ts} - g_{tu} - g_{us}, \dots, \delta^2 = 0$

$$0 \rightarrow \mathbb{R} \rightarrow \mathcal{C}_1 \xrightarrow{\delta} \mathcal{C}_2 \xrightarrow{\delta} \mathcal{C}_3 \xrightarrow{\delta} \dots$$

Then $\delta f = a \Leftrightarrow \delta a = 0$.

- ▶ Small 2-increments cannot be exact: $a_{ts} = o(|t - s|) \Rightarrow a \neq \delta f$
- ▶ Unique decomposition: $a = \delta f + o(|t - s|)$?
Yes, if obstruction δa is small:

Theorem

If $\delta a_{tus} = o(|t - s|)$, then $\exists! f \in \mathcal{C}_1, r \in \mathcal{C}_2^{1+}$ such that

$$a = \delta f + r, \quad \delta f = (1 - \Lambda \delta)a$$

Examples

- ▶ Convergence of sums:

$$S_{t_0} = \sum_i a_{t_{i+1}t_i} = \sum_i (\delta f)_{t_{i+1}t_i} + \sum_i (r)_{t_{i+1}t_i} = (\delta f)_{t_0} + \sum_i o(|t_{i+1} - t_i|) \rightarrow f_t - f_0$$

- ▶ Young integrals: $x \in C^\gamma$, $\gamma > 1/2$ $a_{ts} = \varphi(x_s)\delta x_{ts}$

$$\delta a_{tus} = \delta \varphi(x)_{tu} \delta x_{us} = o(|t - s|^{2\gamma}) \Rightarrow \delta f = (1 - \Lambda \delta)a =: \int \varphi(x) dx$$

- ▶ NCG & Λ map. $L^2(\mathbb{R})$, $dg = [F, g]$, $F^2 = c$,

$$(df)_{ts} = \frac{f_t - f_s}{t - s} \quad \int fdg = \text{Tr}_\omega(fdg) = \frac{1}{2c} \text{Tr}_\omega(Fdfdg)$$

so

$$\Lambda(\delta f \delta g)_{-\infty, \infty} = -\frac{1}{2c} \text{Tr}_\omega(Fdfdg)$$

(Step-2) Rough paths

Rough integrals: $X^\bullet = \delta x$, $\delta X^{[\bullet]} = X^\bullet X^\bullet$, $X^\bullet \in \mathcal{C}_2^\gamma$, $X^{[\bullet]} \in \mathcal{C}_2^{2\gamma}$ ($\gamma > 1/3$)

$$\oint \varphi(x) dx = (1 - \Lambda \delta) \underbrace{(\varphi(x) X^\bullet + \varphi'(x) X^{[\bullet]})}_{\delta(\cdot) \in \mathcal{C}_3^{3\gamma > 1}},$$

$$\delta(\varphi(x) X^\bullet + \varphi'(x) X^{[\bullet]}) = (-\delta \varphi(x) + \varphi'(x) X^\bullet) X^\bullet - \delta \varphi'(x) X^{[\bullet]}$$

- ▶ Continuous map: $(\varphi, X^\bullet, X^{[\bullet]}) \mapsto \oint \varphi(x) dx$
- ▶ Renormalized sums: $\sum_i (\varphi(x_{t_i}) X_{t_{i+1}t_i}^\bullet + \varphi'(x_{t_i}) X_{t_{i+1}t_i}^{[\bullet]}) \rightarrow \oint \varphi(x) dx$
- ▶ $\oint dx dx = X^{[\bullet]}$
- ▶ A finite number of iterated integrals determines all the other integrals.

Branched rough paths

The only data we need to build the family $\{X^\tau\}_{\tau \in \mathcal{T}_\mathcal{L}}$ is a family of maps $\{I^a\}_{a \in \mathcal{L}}$ from \mathcal{C}_2 to \mathcal{C}_2 satisfying certain properties.

Definition

An *integral* is a linear map $I : \mathcal{D}_I \rightarrow \mathcal{D}_I$ on an unital sub-algebra $\mathcal{D}_I \subset \mathcal{C}_2^+$ for which $I(hf) = I(h)f, \forall h \in \mathcal{D}_I, f \in \mathcal{C}_1$ and

$$\delta I(h) = I(e)h + \sum_i I(h^{1,i})h^{2,i} \quad \text{when } h \in \mathcal{D}_I, \delta h = \sum_i h^{1,i}h^{2,i} \text{ and } h^{1,i} \in \mathcal{D}_I$$

Then $X^{\bullet a} = I^a(e), \quad X^{[\tau^1 \dots \tau^k]_a} = I^a(X^{\tau^1 \dots \tau^k}), \quad X^{\tau^1 \dots \tau^k} = X^{\tau^1} \circ \dots \circ X^{\tau^k}.$

Tree multiplicative property still holds: $\delta X^\tau = X^{\Delta' \tau}.$

Geometric rough paths

Integrals are not necessarily Rota-Baxter maps: e.g. Itô's stochastic integral

$$\int_0^t f_s dx_s \int_0^t g_s dx_s = \int_0^t f_s \int_0^s g_u dx_u dx_s + \int_0^t g_s \int_0^s f_u dx_u dx_s + \int_0^t f_s g_s ds$$

$$I(f)I(g) = I(I(f)g) + I(fI(g)) + J(fg), \quad J(f)I(g) = J(fI(g)) + I(gJ(f))$$

Solution to $dy = ydx$, $y_0 = 1$: $y_t = \exp(x_t - t/2)$.

When they are Rota-Baxter we have shuffle relations:

$$I^{a_1}(\dots I^{a_n}(1)) \circ I^{b_1}(\dots I^{b_m}(1)) = \sum_{\bar{c} \in \text{Sh}(\bar{a}, \bar{b})} I^{c_1}(\dots I^{c_{n+m}}(1)) \quad (3)$$

This relation reduces X^τ for $\tau \in \mathcal{T}_{\mathcal{L}}$ to a linear combination of $\{X^\sigma\}_{\sigma \in \mathcal{T}_{\mathcal{L}}^{\text{Chen}}}$.
These are *geometric rough-paths*: the closure of smooth rough paths.

Growing a branched rough path

Fix $\gamma \in (0, 1]$, consider $q_\gamma : \mathcal{F} \rightarrow \mathbb{R}_+$ on forests as $q_\gamma(\tau) = 1$ for $|\tau| \leq 1/\gamma$ and

$$q_\gamma(\tau) = 1, \text{ if } |\tau| \leq 1/\gamma \quad q_\gamma(\tau) = \frac{1}{2^{\gamma|\tau|}} \sum q_\gamma(\tau^{(1)})q_\gamma(\tau^{(2)}) \text{ otherwise}$$

$$q_\gamma(\tau_1 \cdots \tau_n) = q_\gamma(\tau_1) \cdots q_\gamma(\tau_n).$$

Theorem

Given a partial homomorphism $X : \mathcal{A}_n \mathcal{T}_\mathcal{L} \rightarrow \mathcal{C}_2$ satisfying the multiplicative property

$$|X_{ts}^\tau| \leq BA^{|\tau|} q_\gamma(\tau) |t - s|^{\gamma|\tau|}, \quad \tau \in \mathcal{T}_\mathcal{L}^n \quad (4)$$

with $\gamma(n+1) > 1$, then $\exists! X : \mathcal{A} \mathcal{T}_\mathcal{L} \rightarrow \mathcal{C}_2$ such that eq. (4) holds $\forall \tau \in \mathcal{T}_\mathcal{L}$.

Construction via the equation: $X^\tau = \Lambda(X^{\Delta' \tau})$.

Speed of growth

Conjecture

$$q_\gamma(\tau) \asymp C(\tau!)^{-\gamma}$$

True for linear Chen trees $\mathcal{T}^{\text{Chen}}$:

$$\sum_{k=0}^n \frac{a^{\gamma k} b^{\gamma(n-k)}}{(k!)^\gamma (n!)^\gamma} \leq c_\gamma \frac{(a+b)^{\gamma n}}{(n!)^\gamma}, \quad \gamma \in (0, 1], \quad a, b \geq 0$$

Variant of Lyons' neo-classical inequality

$$\sum_{k=0}^n \frac{a^{\gamma k} b^{\gamma(n-k)}}{(\gamma k)! [\gamma(n-k)n]!} \leq c_\gamma \frac{(a+b)^{\gamma n}}{(\gamma n)!}$$

“neo-classical tree inequality”?

$$\sum \frac{a^{\gamma|\tau^{(1)}|} b^{\gamma|\tau^{(2)}|}}{(\tau^{(1)}!)^\gamma (\tau^{(2)}!)^\gamma} \leq c_\gamma \frac{(a+b)^{\gamma|\tau|}}{(\tau!)^\gamma}$$

OK for $\gamma = 1$: tree binomial formula.

Controlled paths

Definition

Let n the largest integer such that $n\gamma \leq 1$. For any $\kappa \in (1/(n+1), \gamma]$ a path y is a κ -weakly controlled by X if

$$\delta y = \sum_{\tau \in \mathcal{F}_{\mathcal{L}}^{n-1}} X^\tau y^\tau + y^\sharp, \quad \delta y^\tau = \sum_{\sigma \in \mathcal{F}_{\mathcal{L}}^{n-1}} \sum_{\rho} c'(\sigma, \tau, \rho) X^\rho y^\sigma + y^{\tau, \sharp}, \quad \tau \in \mathcal{F}_{\mathcal{L}}^{n-1}$$

with $y^\tau \in \mathcal{C}_2^{|\tau|\kappa}$, $y^\sharp, \tau \in \mathcal{C}_2^{(n-|\tau|)\kappa}$. Then we write $y \in \Omega_\kappa(X; V)$.

Lemma (Stability)

Let $\varphi \in C_b^n(\mathbb{R}^k, \mathbb{R})$ and $y \in \Omega_\kappa(X; \mathbb{R}^k)$, then $z_t = \varphi(y_t)$ is a weakly controlled path, $z \in \Omega_\kappa(X; \mathbb{R})$ where its coefficients are given by

$$z^\tau = \sum_{m=1}^{n-1} \sum_{|\bar{b}|=m} \frac{\varphi_{\bar{b}}(y)}{m!} \sum_{\substack{\tau_1, \dots, \tau_m \in \mathcal{F}_{\mathcal{L}}^{n-1} \\ \tau_1 \dots \tau_m = \tau}} y^{\tau_1, b_1} \dots y^{\tau_m, b_m}, \quad \tau \in \mathcal{F}_{\mathcal{L}}^{n-1}$$

Integration of controlled paths

Theorem

The integral maps $\{I^a\}_{a \in \mathcal{L}}$ can be extended to maps $I^a : \mathcal{Q}_\kappa(X) \rightarrow \delta\mathcal{Q}_\kappa(X)$

$$y \in \mathcal{Q}_\kappa(X) \mapsto \delta z = I^a(y) = X^{\bullet a} z^{\bullet a} + \sum_{\tau \in \mathcal{T}_\mathcal{L}^n} X^\tau z^\tau + z^b, \quad (5)$$

where $z^b \in \mathcal{C}_2^{\kappa(n+1)}$, $z^{\bullet a} = y$, $z^{[\tau]a} = y^\tau$ and zero otherwise.

Remark

If $y \in \mathcal{Q}_\kappa(X; \mathbb{R}^n \otimes \mathbb{R}^d)$ then $\{J^b(\cdot) = \sum_{a \in \mathcal{L}} I^a(y^{ab} \cdot)\}_{b \in \mathcal{L}_1}$ defines a family of integrals with an associated branched rough path Y indexed by $\mathcal{T}_{\mathcal{L}_1}$. An explicit recursion is

$$Y^{\bullet b} = \sum_{a \in \mathcal{L}} I^a(y^{ab}), \quad Y^{[\tau^1 \dots \tau^k]b} = \sum_{a \in \mathcal{L}} I^a(y^{ab} Y^{\tau^1} \circ \dots \circ Y^{\tau^k}), \quad b \in \mathcal{L}_1$$

Example

$$\delta y = X^\bullet y^\bullet + X^{\mathbf{I}} y^{\mathbf{I}} + X^{\bullet\bullet} y^{\bullet\bullet} + X^{\mathbf{Y}} y^{\mathbf{Y}} + X^{\mathbf{I}\bullet} y^{\mathbf{I}\bullet} + X^{\mathbf{Y}\mathbf{Y}} y^{\mathbf{Y}\mathbf{Y}} + X^{\bullet\bullet\bullet} y^{\bullet\bullet\bullet} + X^{\mathbf{I}\mathbf{I}} y^{\mathbf{I}\mathbf{I}} + y^\#$$

$$\delta y^\bullet = X^\bullet (y^{\mathbf{I}} + 2y^{\bullet\bullet}) + X^{\mathbf{I}} (y^{\mathbf{I}} + y^{\mathbf{I}\bullet}) + X^{\bullet\bullet} (y^{\mathbf{I}\bullet} + y^{\mathbf{Y}} + 3y^{\bullet\bullet\bullet}) + y^{\bullet\bullet\#}$$

$$\delta y^{\mathbf{I}} = X^\bullet (y^{\mathbf{I}\bullet} + 2y^{\mathbf{Y}} + y^{\mathbf{I}\mathbf{I}}) + y^{\mathbf{I}\mathbf{I}\#}$$

$$\delta y^{\bullet\bullet} = X^\bullet (y^{\mathbf{I}\bullet} + y^{\bullet\bullet\bullet}) + y^{\bullet\bullet\bullet\#}$$

$$\delta y^{\mathbf{Y}} = y^{\mathbf{Y}\#} \quad \delta y^{\mathbf{I}\bullet} = y^{\mathbf{I}\bullet\#} \quad \delta y^{\bullet\bullet\bullet} = y^{\bullet\bullet\bullet\#} \quad \delta y^{\mathbf{I}\mathbf{I}} = y^{\mathbf{I}\mathbf{I}\#}$$

$$\begin{aligned} \delta z = \delta I(y) &= X^\bullet y + X^{\mathbf{I}} y^\bullet + X^{\mathbf{I}\mathbf{I}} y^{\mathbf{I}} + X^{\mathbf{Y}} y^{\bullet\bullet} + X^{\mathbf{Y}\mathbf{I}\bullet} y^{\mathbf{I}\bullet} + X^{\mathbf{Y}\mathbf{Y}} y^{\mathbf{Y}} + X^{\mathbf{Y}\bullet\bullet} y^{\bullet\bullet\bullet} + X^{\mathbf{I}\mathbf{I}\mathbf{I}} y^{\mathbf{I}\mathbf{I}} + z^b \\ &= X^\bullet z^\bullet + X^{\mathbf{I}} z^{\mathbf{I}} + X^{\mathbf{I}\mathbf{I}} z^{\mathbf{I}\mathbf{I}} + X^{\mathbf{Y}} z^{\mathbf{Y}} + z^\# \end{aligned}$$

with

$$z^b = \Lambda \left[X^\bullet y^\# + X^{\mathbf{I}} y^{\bullet\#} + X^{\mathbf{I}\mathbf{I}} y^{\mathbf{I}\#} + X^{\mathbf{Y}} y^{\bullet\bullet\#} + X^{\mathbf{Y}\mathbf{I}\bullet} y^{\mathbf{I}\bullet\#} + X^{\mathbf{Y}\mathbf{Y}} y^{\mathbf{Y}\#} + X^{\mathbf{Y}\bullet\bullet} y^{\bullet\bullet\bullet\#} \right].$$

Rough differential equations

Take vectorfields $\{f_a \in C_b^n(\mathbb{R}^k; \mathbb{R}^k)\}_{a \in \mathcal{L}}$ and integral maps $\{I^a\}_{a \in \mathcal{L}}$ and consider the *rough differential equation*

$$\delta y = I^a(f_a(y)), \quad y_0 = \eta \in \mathbb{R}^k \quad (6)$$

in the time interval $[0, T]$.

Theorem

The rough differential equation (6) has a global solution $y \in \mathcal{Q}_\gamma(X; \mathbb{R}^k)$ for any initial condition $\eta \in \mathbb{R}^k$. If the vectorfields are C_b^{n+1} the solution is unique and has Lipschitz dependence on data.

The KdV equation

1d periodic KdV equation:

$$\partial_t u(t, \xi) + \partial_\xi^3 u(t, \xi) + \frac{1}{2} \partial_\xi u(t, \xi)^2 = 0, \quad u(0, \xi) = u_0(\xi), \quad (t, \xi) \in \mathbb{R} \times \mathbb{T}$$

where initial condition $u_0 \in H^\alpha(\mathbb{T})$, $\mathbb{T} = [-\pi, \pi]$. Linear part: Airy group $U(t)$ (isometries on H^α). Go to Fourier variables and let $v_t = U(-t)u_t$:

$$v_t(k) = v_0(k) + \frac{ik}{2} \sum'_{k_1} \int_0^t e^{-i3kk_1k_2s} v_s(k_1) v_s(k_2) ds, \quad t \in [0, T], k \in \mathbb{Z}_*$$

where $k_2 = k - k_1$ and $v_0(k) = u_0(k)$. Restrict to $v_0(0) = 0$. It has the form

$$v_t = v_s + \int_s^t \dot{X}_\sigma(v_\sigma, v_\sigma) d\sigma, \quad t, s \in [0, T].$$

where $\dot{X}_\sigma(\varphi, \varphi) = \frac{ik}{2} \sum'_{k_1} e^{-i3kk_1k_2\sigma} \varphi(k_1) \varphi(k_2)$.

The KdV equation

Expansion

$$\delta v_{ts} = X^\bullet(v^{\times 2}) + X^\dagger(v^{\times 3}) + X^{\ddagger}(v^{\times 4}) + X^\heartsuit(v^{\times 4}) + r \quad (7)$$

with multi-linear operators X^τ :

$$X_{ts}^\bullet(\varphi_1, \varphi_2) = \int_s^t \dot{X}_\sigma(\varphi_1, \varphi_2) d\sigma;$$

$$X_{ts}^{[\tau^1]}(\varphi_1, \dots, \varphi_{m+1}) = \int_s^t \dot{X}_\sigma(X_{\sigma s}^{\tau^1}(\varphi_1, \dots, \varphi_m), \varphi_{m+1}) d\sigma$$

and

$$X_{ts}^{[\tau^1 \tau^2]}(\varphi_1, \dots, \varphi_{m+n}) = \int_s^t \dot{X}_\sigma(X_{\sigma s}^{\tau^1}(\varphi_1, \dots, \varphi_m), X_{\sigma s}^{\tau^2}(\varphi_{m+1}, \dots, \varphi_{m+n})) d\sigma.$$

Eq.7 is a rough equation which can be solved with fixed-point:

$$\delta v = (1 - \Lambda \delta)[X^\bullet(v^{\times 2}) + X^\dagger(v^{\times 3})]$$

Shadows of the conservation law

Lemma

$$\langle \varphi_1, \dot{X}_s(\varphi_2, \varphi_3) \rangle + \langle \varphi_2, \dot{X}_s(\varphi_1, \varphi_3) \rangle + \langle \varphi_3, \dot{X}_s(\varphi_2, \varphi_1) \rangle = 0, \quad s \in [0, T]$$

$$\langle \varphi, X_{ts}(\varphi, \varphi) \rangle = 0 \quad 2\langle \varphi, X_{ts}^2(\varphi, \varphi, \varphi) \rangle + \langle X_{ts}(\varphi, \varphi), X_{ts}(\varphi, \varphi) \rangle = 0$$

$$\begin{aligned} [\delta \langle v, v \rangle]_{ts} &= 2\langle X_{ts}(v_s, v_s) + X_{ts}^2(v_s, v_s, v_s) + v_{ts}^b, v_s \rangle \\ &\quad + \langle X_{ts}(v_s, v_s), X_{ts}(v_s, v_s) \rangle + 2\langle X_{ts}(v_s, v_s), v_{ts}^\# \rangle + \langle v_{ts}^\#, v_{ts}^\# \rangle \\ &= 2\langle v_{ts}^b, v_s \rangle + 2\langle X_{ts}(v_s, v_s), v_{ts}^\# \rangle + \langle v_{ts}^\#, v_{ts}^\# \rangle = O(|t - s|^{3\gamma}) \end{aligned}$$

Theorem (Integral conservation law)

If v is a solution of KdV then $|v_t|_0^2 = |v_0|_0^2$ for any t .

The NS equation

The d -dimensional NS equation (or the Burgers' equation) have the abstract form

$$u_t = S_t u_0 + \int_0^t S_{t-s} B(u_s, u_s) ds. \quad (8)$$

S bounded semi-group on \mathcal{B} , B symmetric bilinear operator.

Define $d(\tau)$ -multilinear operator by

$$X_{ts}^\bullet(\varphi^{\times 2}) = \int_s^t S_{t-u} B(S_{u-s} \varphi, S_{u-s} \varphi) du$$

$$X_{ts}^{[\tau^1]}(\varphi^{\times (d(\tau^1)+1)}) = \int_s^t S_{t-u} B(X_{us}^{\tau^1}(\varphi^{\times d(\tau^1)}), \varphi) du$$

and

$$X_{ts}^{[\tau^1 \tau^2]}(\varphi^{\times (d(\tau^1)+d(\tau^2))}) = \int_s^t S_{t-u} B(X_{us}^{\tau^1}(\varphi^{\times d(\tau^1)}), X_{us}^{\tau^2}(\varphi^{\times d(\tau^2)})) du$$

where $d(\tau)$ is an appropriate degree function.

Bounds on the operators and regularity

The X operators allow bounds in \mathcal{B} of the form

$$|X^\tau(\varphi^{\times d(\tau)})|_{\mathcal{B}} \leq C \frac{|t-s|^{\varepsilon|\tau|}}{(\tau!)^\varepsilon} |\varphi|_{\mathcal{B}}^{d(\tau)}$$

where $\varepsilon \geq 0$ is a constant depending on the particular Banach space \mathcal{B} we choose.

We have the (norm convergent) series representation

$$u_t = S_t u_0 + \sum_{\tau \in \mathcal{J}_B} X_{t0}^\tau(u_0^{\times d(\tau)}) \quad (9)$$

which gives local solutions to NS.

Regularity: $|u(k)| \leq C e^{-|k|\sqrt{t}}$ by controlling growth of the terms in the series.

Convolution integrals

- ▶ A cochain complex $(\hat{C}_*, \hat{\delta})$ adapted to the study of convolution integrals.
- ▶ Coboundary $\tilde{\delta}h = \delta h - ah - ha$ with $a_{ts} = S_{t-s} - \text{Id}$ the 2-increment associated to the semi-group (parallel transport).
- ▶ Associated integration theory ($\tilde{\Lambda}$ -map as inverse to $\tilde{\delta}$).
- ▶ Algebraic relations , e.g.:

$$\tilde{\delta}X^\bullet(\varphi^{\times 3}) = X^\bullet(X^\bullet(\varphi^{\times 2}), \varphi)$$

- ▶ Applications to stochastic partial differential equations (SPDEs):

$$u_t = S_t u_0 + \int_0^t S_{t-s} dw_s f(u_s)$$

Perspectives & open problems

- ▶ Rough integrals as renormalized integrals
- ▶ Growth of X and generalized B-series:

$$\sum_{\tau} c_{\tau} \frac{a^{|\tau|}}{(\tau!)^{\varepsilon}}$$

- ▶ Birkhoff decomposition for PDEs (cf. ERGE)
- ▶ Scaling in PDEs (RG):
 - ▶ Blowup of solutions via series methods (cf. Sinai for cNS)
 - ▶ Long-time asymptotics
- ▶ Nonperturbative solutions of DSE
- ▶ Hochschild cohomology for (\mathcal{C}, δ)