

Infinite dimensional rough dynamics

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Platus ante annos duos tresve tibi communicavit, de quā tu, suggestore Collinge,
 rescripsisti tandem mihi ~~tibi~~ omnis tiam innotuisse. Diversa ratione in eam incidimus.
 Nam res non eget demonstracione propterea operor. Habilis meo fundamento non
 potuit tangentes alter ducere, nisi volens de recta via deviaret. Quin etiam non hic
 pertinet ad equationes radicalibus unam vel ultram qz, indefinita quantitatam in-
 volventibus atque affectis, sed abs qz aliquā talium equationum reductionē (quae
 opus plerumqz redderet immensum) tangentem confestim duicar. et eodem modo
 se res habet in questionibus de Maximis et minimis, alijs qz quibusdam de
 quibus jam non loquor. ~~ad hanc harē operationē~~ Fundamentū hū
 operationum salī obvium quidem, quoniam jam non possum explicacionē ejus profici-
 sic pollici, celavi. Et accd a 13 eff 7 i 3 c 9 n 4 0 4 q rr 4 5 8 4 1 2 v x. Hoc fundamen-
 tū conatus sum tiam reddere Speculationes de Quadratura curvarum simpliciorē, pervenit
 ad Theorematā quēdam generalia. et ut candide agam ecce primum Theo-
 rem.

Ad curvam aliquam sit $dZ^{\theta} \times \varepsilon + fZ^{\eta}$ ordinatio applicata termino dia-
 metri seu basi Z normaliter insitens: ubi literæ d, ε, f denotant quaslibet
 quantitates datas, & θ, η, λ indices potestatu sive digitalium quantitatum quibus
 effectio sunt. f ac $\frac{\theta+1}{n} = r$. $\lambda + s = s$. $\frac{d}{f^n} \times \varepsilon + fZ^n \lambda + 1 = Q$. & $r n - n = \pi$, &
 area curva sit Q in $\frac{Z^n}{s} - \frac{r-1}{s-1} \times \frac{\varepsilon A}{f Z^n} + \frac{r-2}{s-2} \times \frac{\varepsilon B}{f Z^n} - \frac{r-3}{s-3} \times \frac{\varepsilon C}{f Z^n} + \frac{r-4}{s-4} \times \frac{\varepsilon D}{f Z^n}$ &c ~

literis A, B, C, D et ε denotantibus terminos proxime antecedentes, nempe A
 terminum Z^n , B terminum $- \frac{r-1}{s-1} \times \frac{\varepsilon A}{f Z^n}$ &c. Hec series ubi r fractio est
 vel numerus negativus, continuaatur in infinitum: ubi vero r integer est et affirmati-
 visus continuaatur ad tot terminos tantum quos sunt unitates in eodem r , et sic
 exhibet geometricam quadraturam Curve. Rem exempli illustro.

*“Data aequatione quotcunque fluentes quantitates involvente,
fluxiones invenire; et vice versa”*

(I. Newton, letter to Henry Oldenburg, 24 October 1676)

Solving the controlled ODE in \mathbb{R}^d

$$\dot{y}(t) = V_\alpha(y(t))\dot{x}^\alpha(t), \quad t \geq 0,$$

with $(V_\alpha)_\alpha$ family of vector fields and $y(0)$ given, is equivalent to asking for a function $y: \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}^d$ such that

$$y(t) - y(s) = V_\alpha(y(s))(x^\alpha(t) - x^\alpha(s)) + o(|t-s|), \quad 0 \leq s \leq t.$$

General references on RP/RS:

Lyons '98, Davie, Lyons-Qian, Friz–Victoir, Friz–Hairer, Hairer.

Talk based on joint work with I. Bailleul, A. Deya, M. Hofmanova, S. Tindel.

Goal: Replace differential/integral description with *non-infinitesimal* local one.

$$\delta y(s, t) := y(t) - y(s) = A(s, t) + R(s, t)$$

- A is a “germ” for the dynamics of y :

$$A(s, t) = V(y(s))X^1(s, t) + V_2(y(s))X^2(s, t) + \dots$$

- the equation holds modulo error term $R(s, t)$ of order $o(|t - s|)$
- **Key insight.** this decomposition is rigid: to each given A there can correspond only one pair (y, R) :

$$|\delta y(s, t) - \delta \tilde{y}(s, t)| = |R(s, t) - \tilde{R}(s, t)| = o(|t - s|)$$

Explicit bounds on R in terms of the “coherence” of A

$$\delta A(s, u, t) := A(s, t) - (A(s, u) + A(u, t)), \quad s \leq u \leq t$$

Lemma Assume that

$$|\delta A(s, u, t)| \leq \|\delta A\|_z |t - s|^z$$

for some $z > 1$, then there exists a unique y such that

$$\delta y(s, t) = A(s, t) + R(s, t), \quad |R(s, t)| = o(|t - s|)$$

and moreover

$$|R(s, t)| \leq C_z \|\delta A\|_z |t - s|^z.$$

This result holds for general regular controls $\omega(s, t)$ (replacing $|t - s|$):

$$\omega(s, u) + \omega(u, t) \leq \omega(s, t), \quad |t - s| \rightarrow 0 \Rightarrow \omega(s, t) \rightarrow 0$$

Local expansion of ODEs:

$$y(t) = y(s) + \underbrace{V_\alpha(y(s)) \int_s^t dx^\alpha(r)}_{X^{1,\alpha}(s,t)} + \underbrace{V_{2,\alpha\beta}(y(s)) \int_s^t \int_s^r dx^\alpha(w) dx^\beta(r)}_{X^{2,\alpha\beta}(s,t)} + \dots$$

with $V_{2,\alpha\beta}(\xi) = V_\alpha(\xi) \cdot \nabla V_\beta(\xi)$.

Definition 1 A (step-2) rough path $\mathbb{X} = (X^1, X^2)$ is a pair such that

$$\delta X^1(s, u, t) = 0, \quad \delta X^2(s, u, t) = X^1(s, u) X^1(u, t)$$

$$|X^1(s, t)| + |X^2(s, t)|^{1/2} \leq \|\mathbb{X}\|_\gamma |t - s|^\gamma$$

for some $\gamma \geq 1/3$.

[Lyons '98]

- ▷ Let $x \in C^\gamma$ and $(x^\varepsilon)_\varepsilon$ some family of smooth approximations $x^\varepsilon \rightarrow x$ in C^γ .
- ▷ Smooth approximations by ODEs

$$\dot{y}^\varepsilon = V(y^\varepsilon) \dot{x}^\varepsilon(t)$$

- ▷ Taylor expansion gives

$$\delta y^\varepsilon(s, t) = A^\varepsilon(s, t) + R^\varepsilon(s, t)$$

$$A^\varepsilon(s, t) = V(y^\varepsilon(s)) X^{\varepsilon, 1}(s, t) + V_2(y^\varepsilon(s)) X^{\varepsilon, 2}(s, t) \quad |R^\varepsilon(s, t)| \leq \| \dot{x}^\varepsilon \|_\infty |t - s|^3$$

- ▷ **Problem:** estimates for the remainder are not uniform in $\varepsilon \rightarrow 0$.

► Uniform estimates for R^ε from the coherence of the germ A^ε itself

$$\delta A^\varepsilon(s, u, t) = -\delta V(y^\varepsilon)(s, u) X^{\varepsilon, 1}(u, t) + V_2(y^\varepsilon(s)) \delta X^{\varepsilon, 2}(s, u, t) - \delta V_2(y^\varepsilon)(s, u) X^{\varepsilon, 2}(u, t)$$

$$= -\underbrace{(\delta V(y^\varepsilon)(s, u) - V_2(y^\varepsilon(s)) X^{\varepsilon, 1}(s, u)) X^{\varepsilon, 1}(u, t)}_{O(|R^\varepsilon(s, t)|) + O(|t-s|^{2\gamma})} - \underbrace{\delta V_2(y^\varepsilon)(s, u)}_{O(|R^\varepsilon(s, t)|) + O(|t-s|^\gamma)} \underbrace{X^{\varepsilon, 2}(u, t)}_{O(|t-s|^{2\gamma})}$$

$$\|R^\varepsilon\|_{2\gamma} := \sup_{s, t} \frac{|R^\varepsilon(s, t)|}{|t-s|^{2\gamma}}.$$

► If $3\gamma > 1$ the sewing lemma gives

$$\begin{aligned} |\delta A^\varepsilon(s, u, t)| &\lesssim (\|R^\varepsilon\|_{2\gamma} + \|\mathbb{X}^\varepsilon\|_\gamma) \|\mathbb{X}^\varepsilon\|_\gamma |t-s|^{3\gamma} \\ &\Downarrow \\ \|R^\varepsilon\|_{3\gamma} &\lesssim (\|R^\varepsilon\|_{2\gamma} + \|\mathbb{X}^\varepsilon\|_\gamma) \|\mathbb{X}^\varepsilon\|_\gamma \end{aligned}$$

$\|R^\varepsilon\|_{3\gamma} \lesssim_{\|\mathbb{X}^\varepsilon\|_\gamma} 1$ uniformly in $\varepsilon > 0$.

- The limit $y^\varepsilon \rightarrow y$ exists provided $\mathbb{X}^\varepsilon \rightarrow \mathbb{X} = (X^1, X^2)$ in *rough path topology*.
- It satisfies the RDE [Davie]

$$\delta y(s, t) = V(y(s))X^1(s, t) + V_2(y(s))X^2(s, t) + O(|t - s|^{3\gamma}).$$

- Is unique under sufficient regularity for V, V_2 .
- The map $\mathbb{X} \mapsto y = \Phi(\mathbb{X})$ is continuous.
- Rough path limit \mathbb{X} is **not unique** for given x . It holds

$$X^1(s, t) = \tilde{X}^1(s, t) = \delta x(s, t), \quad \tilde{X}^2(s, t) - X^2(s, t) = \delta \varphi(s, t).$$

- The limit RDE is not an ODE (or not that one expects...).

Example Pure area RP: there exists $\mathbb{X}^\varepsilon \rightarrow (0, \delta \varphi)$ with $\varphi \in C^1$. Then

$$\dot{y}^\varepsilon(t) = V(y^\varepsilon(t))\dot{x}^\varepsilon(t) \quad \Rightarrow \quad \dot{y}(t) = V_2(y(t))\dot{\varphi}(t)$$

What about (S)PDEs?

- Works on (singular) parabolic SPDEs: [Hairer!, G.–Imkeller–Perkowski, Kupiainen]
- Works on flow transformations (viscosity solutions, conservation laws, transport equations) [Friz et al., Souganidis–Gess, Hofmanova]

Today: description of distributions satisfying (rough in time) PDEs.

Transport equation

$$\partial_t u(t, x) = \dot{X}^\alpha(t) V_\alpha(x) \nabla u(t, x), \quad t \geq 0.$$

Weak formulation: $u \in L^\infty(\mathbb{R}_+ \times \mathbb{R}^d) \cap C^1(\mathbb{R}_+, (W^{1,1}(\mathbb{R}^d))^*)$

$$u_t(\varphi) = \int_{\mathbb{R}^d} \varphi(x) u(t, x) dx$$

$$\partial_t u_t(\varphi) = u_t(\dot{X}^\alpha(t) (V_\alpha \cdot \nabla)^* \varphi) = u_t(\dot{A}_t^* \varphi), \quad t \geq 0.$$

Rough dynamics: $u \in L^\infty(\mathbb{R}_+ \times \mathbb{R}^d) \cap C^\gamma(\mathbb{R}_+, (W^{1,1}(\mathbb{R}^d))^*)$

$$\delta u(\varphi)_{s,t} = u_s(\mathbb{A}_{s,t}^{1,*} \varphi) + u_s(\mathbb{A}_{s,t}^{2,*} \varphi) + o(|t-s|)$$

where (*rough driver*) $\mathbb{A}_{s,t}^1 = X^{1,\alpha}(s, t) V_\alpha \cdot \nabla$, $\mathbb{A}_{s,t}^2 = X^{2,\alpha\beta}(s, t) (V_\alpha \cdot \nabla)(V_\beta \cdot \nabla)$.

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22

▷ Rough driver: $\delta \mathbb{A}_{s,u,t}^1 = 0 \quad \delta \mathbb{A}_{s,u,t}^2 = \mathbb{A}_{u,t}^1 \mathbb{A}_{s,u}^1$

▷ Germ: $A_{s,t}(\varphi) = u_s(\mathbb{A}_{s,t}^{1,*} \varphi) + u_s(\mathbb{A}_{s,t}^{2,*} \varphi)$

$$\delta A_{s,u,t}(\varphi) = -(\delta u_{s,u} - u_s \mathbb{A}_{s,u}^{1,*})(\mathbb{A}_{u,t}^{1,*} \varphi) - \delta u_{s,u}(\mathbb{A}_{u,t}^{2,*} \varphi)$$

(and using the equation $\delta u_{s,u} = u_s(\mathbb{A}_{s,u}^{1,*} + \mathbb{A}_{s,u}^{2,*}) + R_{s,u}$)

$$= -R_{s,u}(\mathbb{A}_{u,t}^{1,*} \varphi + \mathbb{A}_{u,t}^{2,*} \varphi) - u_s(\mathbb{A}_{s,u}^{2,*} \mathbb{A}_{u,t}^{1,*} \varphi + \mathbb{A}_{s,u}^{1,*} \mathbb{A}_{u,t}^{2,*} \varphi + \mathbb{A}_{s,u}^{2,*} \mathbb{A}_{u,t}^{2,*} \varphi)$$

$$|\delta A(s, u, t)|_{(W^{1,3})^*} \lesssim (\|R\|_{2\gamma, (W^{1,2})^*} + \|R\|_{\gamma, (W^{1,1})^*} + \|\mathbb{A}\|_\gamma) \|\mathbb{A}\|_\gamma |t-s|^{3\gamma}$$

\Downarrow

$$\|R\|_{3\gamma, (W^{1,3})^*} \lesssim (\|R\|_{2\gamma, (W^{1,2})^*} + \|R\|_{\gamma, (W^{1,1})^*} + \|\mathbb{A}\|_\gamma) \|\mathbb{A}\|_\gamma$$

Estimate cannot be closed.

- ▶ Loss of derivatives in the estimate can be compensated by the time regularity via a small interpolation argument, giving

$$\|R\|_{3\gamma, (W^{1,3})^*} \lesssim (\|R\|_{3\gamma, (W^{1,3})^*} + \|\mathbb{A}\|_\gamma) \|\mathbb{A}\|_\gamma$$

and uniform apriori estimate:

$$\|R\|_{\gamma, (W^{1,1})^*} + \|R\|_{2\gamma, (W^{1,2})^*} + \|R\|_{3\gamma, (W^{1,3})^*} \lesssim \|\mathbb{A}\|_\gamma 1.$$

- ▶ Existence of solutions via compactness of smooth approximations using this estimate.

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22

Deterministic strategy for uniqueness of $\partial_t u = V \cdot \nabla u$:

Start with (commutator lemma!)

$$\partial_t u^2 = 2u \partial_t u = 2u V \cdot \nabla u = V \cdot \nabla u^2$$

and integrating over space we get

$$\partial_t \int u^2 = \int (V \cdot \nabla u^2) = - \int \operatorname{div} V u^2.$$

Gronwall

$$\int u_t^2 \leq \int u_0^2 \exp(t \|\operatorname{div} V\|_{L^\infty})$$

$$u_0 = 0 \implies u_t = 0$$

Can we redo it roughly? We need “Ito formula” for the square and (rough) Gronwall...

Product of distributions is dangerous. Tensor product easier.

Consider the dynamics for $U(x, y) = (u \otimes u)(x, y) = u(x)u(y)$.

$$\delta U_{s,t}(\Phi) = U_s(\Gamma_{\mathbb{A},s,t}^{1,*}\Phi) + U_s(\Gamma_{\mathbb{A},s,t}^{2,*}\Phi) + o(|t-s|)$$

with

$$\Gamma_{\mathbb{A},s,t}^1 = \mathbb{A}_{s,t}^1 \otimes \mathbb{I} + \mathbb{I} \otimes \mathbb{A}_{s,t}^1, \quad \Gamma_{\mathbb{A},s,t}^2 = \mathbb{A}_{s,t}^2 \otimes \mathbb{I} + \mathbb{I} \otimes \mathbb{A}_{s,t}^2 + \mathbb{A}_{s,t}^1 \otimes \mathbb{A}_{s,t}^1$$

(we used the property $\mathbb{X}_{s,t}^{1,\alpha} \mathbb{X}_{s,t}^{1,\beta} = \mathbb{X}_{s,t}^{2,\alpha\beta} + \mathbb{X}_{s,t}^{2,\beta\alpha}$)

Another rough driver:

$$\delta \Gamma_{\mathbb{A},s,u,t}^1 = 0, \quad \delta \Gamma_{\mathbb{A},s,u,t}^2 = \Gamma_{\mathbb{A},u,t}^1 \Gamma_{\mathbb{A},s,u}^1.$$

Passage to the diagonal

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22

We want to use the fact that

$$u_t^2(\varphi) = \int u_t^2(x) \varphi(x) dx = \lim_{\varepsilon \rightarrow 0} \iint u_t(x) u_t(y) \varepsilon^{-d} \psi\left(\frac{x-y}{\varepsilon}\right) \varphi\left(\frac{x+y}{2}\right) dx dy = U_t(\Phi_\varepsilon)$$

but $(\Phi_\varepsilon)_\varepsilon$ is a singular family of test functions.

Under appropriate conditions

$$A_{s,t}^\varepsilon(\varphi) = U_s(\Gamma_{\mathbb{A},s,t}^{1,*} \Phi_\varepsilon) + U_s(\Gamma_{\mathbb{A},s,t}^{2,*} \Phi_\varepsilon) \rightarrow u_s^2(\mathbb{A}_{s,t}^{1,*} \varphi) + u_s^2(\mathbb{A}_{s,t}^{2,*} \varphi)$$

and the coherence of this germ can be controlled uniformly in ε (similar to Di Perna–Lions commutator).

Result:

$$\delta u_{s,t}^2(\varphi) = u_s^2(\mathbb{A}_{s,t}^{1,*} \varphi) + u_s^2(\mathbb{A}_{s,t}^{2,*} \varphi) + o(|t-s|)$$

(Itô formula for the square).

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22

Now take $\varphi_R(x) = (1 + |x/R|^2)^{-M}$, then

$$|(V \cdot \nabla)^* \varphi_R(x)| \lesssim \varphi_R(x), \quad |(V \cdot \nabla)^*(V \cdot \nabla)^* \varphi_R(x)| \lesssim \varphi_R(x),$$

and from

$$\delta u_{s,t}^2(\varphi_R) = u_s^2(\mathbb{A}_{s,t}^{1,*} \varphi_R) + u_s^2(\mathbb{A}_{s,t}^{2,*} \varphi_R) + O(|t-s|^{3\gamma})$$

we get

$$h(t) \leq h(s) + h(s) |t-s|^\gamma + C \left(\sup_{r \leq t} h(r) \right) |t-s|^{3\gamma}$$

where $h(t) := u_t^2(\varphi_R)$. A small *rough Gronwall* lemma allows to conclude that

$$\sup_{t \leq T} h(t) \lesssim_T h(0)$$

and from there the uniqueness.

Scalar conservation law with time-dependent fluxes

$$\partial_t u(t, x) = \operatorname{div}(A_\alpha(x, u(t, x))) \dot{X}^\alpha(t)$$

Kinetic formulation : $f(t, x, \xi) := \mathbb{I}_{\xi < u(t, x)}$

$$\partial_t f(t, x, \xi) = V_\alpha(t, x, \xi) \cdot \nabla_{x, \xi} f(t, x, \xi) \dot{X}^\alpha(t) + \partial_\xi m(dt dx d\xi)$$

A solution is a *pair* (f, m) with $f \in L^\infty$ and m a measure on $\mathbb{R}_+ \times \mathbb{R}^d \times \mathbb{R}$.

$$u(t, x) = \int (f(t, x, \xi) - \mathbb{I}_{\xi < 0}) d\xi, \quad -\partial_\xi f(t, x, \xi) = \delta_{u(t, x)}(\xi) \text{ (Young measure)}$$

Rough formulation:

$$\delta f_{s,t}(\varphi) = f_s(\mathbb{A}_{s,t}^{1,*} \varphi) + f_s(\mathbb{A}_{s,t}^{2,*} \varphi) + \delta m(\partial_\xi \varphi)$$

Existence via compactness, uniqueness via tensorization.

Scalar deterministic transport + Stratonovic Brownian perturbation

$$du_t = V \cdot \nabla u_t dt + \nabla u_t \circ dB_t.$$

The vectorfield V is not Lipschitz (no uniqueness classically).

Almost sure uniqueness if $V \in C^\varepsilon$ [Flandoli–G.–Priola]. A lot of work recently (Proske et al).

Change of variables: $v(t, x) = u(t, x - B_t)$

$$dv_t(x) = V(x - B_t) \cdot \nabla v_t(x) dt.$$

Rough (Young) dynamics

$$\delta v_{s,t} = \mathbb{A}_{s,t}^1 v_s + o(|t-s|)$$

with $\mathbb{A}_{s,t}^1 = \int_s^t V(x - B_r) dr \cdot \nabla$

Lemma 2 (Catellier–G.) *For any $\varepsilon > 0$ there exists $\gamma > 1/2$ such that*

$$\|x \mapsto \int_s^t V(x - B_r) dr\|_{C^{3/2+\varepsilon}} \lesssim |t-s|^\gamma \|V\|_{C^{1/2+2\varepsilon}}$$

for almost every Brownian path (exceptional set depends on V).

This property guarantees uniqueness of the RTE pathwise via a tensorization argument, no stochastic analysis involved.

[Catellier (via flow transformation), Maurelli (intrinsic)]

Thanks!